

Solvability of a fourth order elliptic problem in a bounded sector, part I

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Abstract

The purpose of this article (composed of two parts) is the study of the generalized dispersal operator of a reaction-diffusion equation in L^p -spaces set in the finite conical domain $S_{\omega,\rho}$ of angle $\omega > 0$ and radius $\rho > 0$ in \mathbb{R}^2 .

This first part is devoted to the behavior of the solution near the top of the cone which is completely described in the weighted Sobolev space $W_{3-\frac{1}{p}}^{4,p}(S_{\omega,\rho_0})$, $0 < \rho_0 \leq \rho$, see Theorem 2.2.

Key Words and Phrases: Fourth order boundary value problem, conical domain, weighted Sobolev spaces.

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1 Introduction

This work required the use of many calculations and non-trivial checks linked, among other, to the theory of sums of linear operators. This is why we were forced to split this work into two more or less independent parts.

We consider the following bounded conical domain

$$S_{\omega,\rho} = \{(x, y) = (r \cos \theta, r \sin \theta) : 0 < r < \rho \text{ and } 0 < \theta < \omega\},$$

and its three edges:

$$\begin{cases} \Gamma_0 &= (0, \rho) \times \{0\} \\ \Gamma_\omega &= \{(r \cos \omega, r \sin \omega) : 0 < r < \rho\} \\ \Gamma_\rho &= \{(\rho \cos \theta, \rho \sin \theta) : 0 < \theta < \omega\}, \end{cases}$$

where $\rho > 0$ is given and $\omega \in (0, 2\pi]$.

Let k be a positive number, f^* be a non-linear reaction function, u_0 be a given function and n be the outwards normal unit vector to $\partial S_{\omega,\rho}$.

We recall that the resolution of the generalized following reaction-diffusion problem

$$\begin{cases} \frac{\partial u}{\partial t}(t, x, y) &= -\Delta_{(x,y)}^2 u(t, x, y) + k\Delta_{(x,y)} u(t, x, y) + f^*(u(t, x, y)) & \text{in } \mathbb{R}_+ \times S_{\omega,\rho} \\ u(0, x, y) &= u_0(x, y), (x, y) \in S_{\omega,\rho} \\ u(t, \sigma) &= \frac{\partial u}{\partial n}(t, \sigma) = 0, (t, \sigma) \in \mathbb{R}_+ \times \Gamma_0 \cup \Gamma_\omega \\ u(t, \sigma) &= \frac{\partial^2 u}{\partial n^2}(t, \sigma) = 0, (t, \sigma) \in \mathbb{R}_+ \times \Gamma_\rho, \end{cases} \quad (1)$$

needs, in a first step, to solve the following linear stationary problem

$$\begin{cases} \Delta^2 u - k\Delta u = f & \in L^p(S_{\omega,\rho}), \quad p \in (1, +\infty) \\ u = \frac{\partial u}{\partial n} = 0 & \text{on } \Gamma_0 \cup \Gamma_\omega \\ u = \frac{\partial^2 u}{\partial n^2} = 0 & \text{on } \Gamma_\rho. \end{cases} \quad (2)$$

This first study will allow us to determine, by an analogous calculus, the resolvent of the corresponding operator by solving the spectral problem

$$\begin{cases} \Delta^2 u - k\Delta u - \lambda u = f & \in L^p(S_{\omega,\rho}) \\ u = \frac{\partial u}{\partial n} = 0 & \text{on } \Gamma_0 \cup \Gamma_\omega \\ u = \frac{\partial^2 u}{\partial n^2} = 0 & \text{on } \Gamma_\rho, \end{cases}$$

and then to estimate the resolvent operator in view to obtain the generation of an analytic semigroup as in Labbas, Maingot and Thorel [8]. In the last step, the fixed point method can be applied to solve (1).

In this first part, we will focus ourselves on the study of problem (2). This work is a natural continuation of the one studied in Labbas, Maingot, Manceau and Thorel [6].

The originality of this work lies in the fact that the open set $S_{\omega,\rho}$ is conical whereas in the cited works above, it was cylindrical and in the fact that the spatial operator is composed by a linear combination of a laplacian and a bilaplacian operators.

Such problems, set in conical domains, model many concrete situations related to pollution for instance.

After some variables and functions changes, problem (2) will be written as a abstract sum of unbounded linear operators in a Banach space, see (14). Therefore, we will use the sum theory carried out in part II to solve (14), see Labbas, Maingot and Thorel [7].

This work is inspired by the one done by G. Geymonat and P. Grisvard in [4] and P. Grisvard in [5], where the authors have considered, in a hilbertian framework, the following boundary problem

$$\begin{cases} \Delta^2 u = 0 & \text{in } S_\omega \\ u = \frac{\partial u}{\partial n} = 0 & \text{on } \Gamma_0 \cup \Gamma_\omega, \end{cases}$$

where S_ω is the infinite conical domain

$$S_\omega = \{(x, y) = (r \cos \theta, r \sin \theta) : r > 0 \text{ and } 0 < \theta < \omega\}.$$

The author has proved that the solution of this problem is written as a "superposition" of particular solutions with separate variables of the form $\chi_{1,j}(r)\chi_{2,j}(\theta)$, for $j \in \mathbb{N}$. The basic tools used are based on the compact operators belonging to the so-called Carleman class and the Fredholm determinants.

Let us recall some known results concerning the biharmonic equation in a conical domain or in a Lipschitz domain. In Pipher and Verchota [11], the authors gave many estimates concerning the solution of the Dirichlet problem in L^p for the biharmonic equation in Lipschitz domain. In Costabel, Dauge and Nicaise [2], the authors have used Mellin transformation in view to give an optimal characterization of the structure of weighted Sobolev spaces with nonhomogeneous norms on finite cones. In Barton and Mayboroda [1], many results are

given for general higher-order elliptic equations in non smooth-domains. In Tami [12], the author has studied the following problem

$$\begin{cases} \Delta^2 u = f & \text{in } S_{\omega,1} \\ u = \Delta u = 0 & \text{on } \partial S_{\omega,1}, \end{cases}$$

where $f \in L^2(S_{\omega,1})$. He has proved the two following results

1. If $\omega < \pi$, the variational solution is written, in the neighbourhood of the corner, as

$$u_\omega = u_{1,\omega} + u_{2,\omega} + u_{3,\omega},$$

with $u_{1,\omega} \in H^{1+\frac{\pi}{\omega}-\varepsilon}$, $u_{2,\omega} \in H^{2+\frac{\pi}{\omega}-\varepsilon}$ and $u_{3,\omega} \in H^4$, for a small $\varepsilon > 0$.

2. If $\omega = \pi$, in the neighbourhood of the corner, the variational solution verifies

$$u_\pi \in H^4.$$

This article is organized as follows. In Section 2, we state our problem in polar coordinates and our main result in Theorem 2.2. In Section 3 we reformulate our problem as a sum of linear unbounded operators. Then, Section 4 is devoted to the proof of Theorem 2.2.

2 Statement of the main result

We introduce the following polar variables function

$$v(r, \theta) = u(r \cos \theta, r \sin \theta) = u(x, y).$$

It is known that the laplacian and the bilaplacian, in polar coordinates, are respectively written as

$$\Delta u = \frac{1}{r^2} \left[\left(r \frac{\partial}{\partial r} \right)^2 + \frac{\partial^2}{\partial \theta^2} \right] v = \frac{\partial^2 v}{\partial r^2} + \frac{1}{r} \frac{\partial v}{\partial r} + \frac{1}{r^2} \frac{\partial^2 v}{\partial \theta^2} := \Lambda_1 v, \quad (3)$$

and

$$\begin{aligned} \Delta^2 u &= \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right)^2 v \\ &= \frac{\partial^4 v}{\partial r^4} + \frac{2}{r^2} \frac{\partial^4 v}{\partial r^2 \partial \theta^2} + \frac{1}{r^4} \frac{\partial^4 v}{\partial \theta^4} + \frac{2}{r} \frac{\partial^3 v}{\partial r^3} - \frac{2}{r^3} \frac{\partial^3 v}{\partial r \partial \theta^2} - \frac{1}{r^2} \frac{\partial^2 v}{\partial r^2} + \frac{4}{r^4} \frac{\partial^2 v}{\partial \theta^2} + \frac{1}{r^3} \frac{\partial v}{\partial r} \\ &:= \Lambda_2 v. \end{aligned} \quad (4)$$

Remark 2.1. We can generalize this work to the dimension n :

$$\Delta u = \frac{\partial^2 v}{\partial r^2} + \frac{n-1}{r} \frac{\partial v}{\partial r} + \frac{1}{r^2} \Delta' v,$$

where Δ' is the Laplace-Beltrami operator on the sphere.

We set

$$f(x, y) = f(r \cos \theta, r \sin \theta) = g(r, \theta).$$

Let $\gamma \in \mathbb{R}$. In the case of the unbounded conical domain

$$S_\omega = \{(x, y) = (r \cos \theta, r \sin \theta) : r > 0 \text{ and } 0 < \theta < \omega\},$$

we will use the following weighted Sobolev spaces of Kondrat'ev type

$$L_\gamma^p(S_\omega) = \left\{ v \text{ measurable on } S_\omega : \int_{S_\omega} |v(r, \theta)|^p r^{p\gamma} dr d\theta < +\infty \right\},$$

and

$$W_\gamma^{m,p}(S_\omega) = \left\{ v \in L_\gamma^p(S_\omega), \forall (i, j) \in \mathbb{N}^2 : 0 \leq i + j \leq m, r^{\gamma+i+j} \frac{\partial^{i+j} v}{\partial r^i \partial \theta^j} \in L^p(S_\omega) \right\}, \quad (5)$$

see, for instance, Definition 2.1 in Costabel, Dauge and Nicaise [2].

In the sequel, the definitions above, for the bounded conical domain $S_{\omega,\rho}$, coincide with

$$L_\gamma^p(S_{\omega,\rho}) = \left\{ v \text{ measurable on } S_{\omega,\rho} : \int_{S_{\omega,\rho}} |v(r, \theta)|^p r^{p\gamma} dr d\theta < +\infty \right\},$$

and

$$W_\gamma^{m,p}(S_{\omega,\rho}) = \left\{ v \in L_\gamma^p(S_{\omega,\rho}), \forall (i, j) \in \mathbb{N}^2 : 0 \leq i + j \leq m, r^\gamma \frac{\partial^{i+j} v}{\partial r^i \partial \theta^j} \in L^p(S_{\omega,\rho}) \right\}, \quad (6)$$

since clearly (6) implies (5) in the bounded conical domain $S_{\omega,\rho}$.

Note that $f \in L^p(S_{\omega,\rho})$ means that $g \in L_{\frac{1}{p}}^p(S_{\omega,\rho})$. In fact, we have

$$\int_{S_{\omega,\rho}} |f(x, y)|^p dx dy = \int_{S_{\omega,\rho}} |g(r, \theta)|^p r dr d\theta,$$

where

$$g(r, \theta) = f(r \cos \theta, r \sin \theta), \quad 0 < r < \rho, \quad 0 < \theta < \omega.$$

Then, in polar coordinates, problem (2) is written in the following form

$$\begin{cases} \Lambda_2 v - k \Lambda_1 v = g & \text{in } S_{\omega,\rho} \\ v(r, 0) = v(r, \omega) = \frac{\partial v}{\partial \theta}(r, 0) = \frac{\partial v}{\partial \theta}(r, \omega) = 0 \\ v(\rho, \theta) = \frac{\partial^2 v}{\partial r^2}(\rho, \theta) = 0, \end{cases} \quad (7)$$

where Λ_1 and Λ_2 are given by (3) and (4).

In this article, we will focus ourselves on the resolution of problem (7) to obtain the behavior of the solution v to problem (7) in L^p -weighted spaces, in the neighborhood of the top of the cone. To this v corresponds a solution u_0 to problem (2) by applying the inverse changes of variables and functions.

To solve problem (7), we will use results given in Labbas, Maingot and Thorel [7] and to this end, we need to consider

$$\tau = \min_{j \geq 1} |\text{Im}(z_j)| > 0,$$

where $(z_j)_{j \geq 1}$ are the solutions of the following transcendent equation

$$(\sinh(z) + z)(\sinh(z) - z) = 0, \quad \text{with } \text{Re}(z) > 0.$$

Actually, according to Fädle [3], we have

$$\tau \simeq 4.21239.$$

We assume that

$$\omega \left(3 - \frac{2}{p} \right) < \tau. \quad (8)$$

Recall that $3 - \frac{2}{p}$ is exactly the Sobolev exponent of the space $W^{3,p}$ in two variables.

Let us remark that we have two cases:

1. If $0 < \omega \leq \frac{\tau}{3} \simeq 0.45\pi$, then (8) is satisfied for all $p \in (1, +\infty)$.
2. If $\frac{\tau}{3} < \omega < \tau \simeq 1.34\pi$, then (8) is satisfied for $1 < p < \frac{2\omega}{3\omega - \tau}$.

Our main result is the following:

Theorem 2.2. Let $g \in L^{\frac{p}{2}}(S_{\omega,\rho})$ with p satisfying assumption (8). Then, there exists $\rho_0 > 0$ such that problem (7) has a unique solution v satisfying

$$v \in W_{3-\frac{1}{p}}^{4,p}(S_{\omega,\rho_0}).$$

Remark 2.3. Note that, we can also verify that we have in addition: for $i = 0, 1, 2$ and $j = 0, 1, 2, 3, 4$ such that $0 \leq i + j \leq 4$

$$\frac{\partial^{i+j}v}{\partial r^i \partial \theta^j} \in L^p(S_{\omega,\rho_0}).$$

In fact, we have

$$\frac{\partial^3 v}{\partial r^3}, \frac{\partial^4 v}{\partial r^3 \partial \theta} \in L_{2-\frac{1}{p}}^p(S_{\omega,\rho_0}) \quad \text{and} \quad \frac{\partial^4 v}{\partial r^4} \in L_{3-\frac{1}{p}}^p(S_{\omega,\rho_0}),$$

see Section 4.2.2; but, these two weighted spaces are not embedded into the space $L^p(S_{\omega,\rho_0})$.

3 Reformulations of problem (7)

3.1 Some preliminary calculus

Let us introduce the auxiliary function $\frac{v}{r}$. Then

$$\begin{aligned} \left(r \frac{\partial}{\partial r} \right)^2 \left(\frac{v}{r} \right) &= \left(r \frac{\partial}{\partial r} \right) \left(r \frac{\partial}{\partial r} \right) \left(\frac{v}{r} \right) \\ &= \frac{v}{r} - \frac{\partial v}{\partial r} + r \frac{\partial^2 v}{\partial r^2} \\ &= \frac{v}{r} - 2 \frac{\partial}{\partial r} \left(r \cdot \frac{v}{r} \right) + r \left(\frac{1}{r} \frac{\partial v}{\partial r} + \frac{\partial^2 v}{\partial r^2} \right) \\ &= -\frac{v}{r} - 2r \frac{\partial}{\partial r} \left(\frac{v}{r} \right) + r \left(\frac{1}{r} \frac{\partial v}{\partial r} + \frac{\partial^2 v}{\partial r^2} \right), \end{aligned}$$

so

$$\Delta u = \left(\frac{1}{r} \frac{\partial v}{\partial r} + \frac{\partial^2 v}{\partial r^2} \right) + \frac{1}{r^2} \frac{\partial^2 v}{\partial \theta^2} = \frac{1}{r} \left[\left(r \frac{\partial}{\partial r} \right)^2 \left(\frac{v}{r} \right) + \frac{v}{r} + 2r \frac{\partial}{\partial r} \left(\frac{v}{r} \right) \right] + \frac{1}{r} \frac{\partial^2}{\partial \theta^2} \left(\frac{v}{r} \right).$$

Moreover, we have

$$\begin{aligned}
\Pi_1 &:= \left(r \frac{\partial}{\partial r}\right)^2 \left[\left(r \frac{\partial}{\partial r}\right)^2 \left[\frac{v}{r}\right] \right] \\
&= \left(r \frac{\partial}{\partial r}\right)^2 \left[\left(r \frac{\partial}{\partial r}\right) \left(-\frac{v}{r} + \frac{\partial v}{\partial r}\right) \right] \\
&= \left(r \frac{\partial}{\partial r}\right)^2 \left[\frac{v}{r} - \frac{\partial v}{\partial r} + r \frac{\partial^2 v}{\partial r^2} \right] \\
&= \left(r \frac{\partial}{\partial r}\right) \left[-\frac{v}{r} + \frac{\partial v}{\partial r} + r^2 \frac{\partial^3 v}{\partial r^3} \right] \\
&= \frac{v}{r} - \frac{\partial v}{\partial r} + r \frac{\partial^2 v}{\partial r^2} + 2r^2 \frac{\partial^3 v}{\partial r^3} + r^3 \frac{\partial^4 v}{\partial r^4},
\end{aligned}$$

and

$$\begin{aligned}
\Pi_2 &:= 2 \left(\frac{\partial^2}{\partial \theta^2} - 1\right) \left(r \frac{\partial}{\partial r}\right)^2 \left(\frac{v}{r}\right) + \left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 \left(\frac{v}{r}\right) \\
&= 2 \left(\frac{\partial^2}{\partial \theta^2} - 1\right) \left(\frac{v}{r} - \frac{\partial v}{\partial r} + r \frac{\partial^2 v}{\partial r^2}\right) + \frac{1}{r} \left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 v \\
&= 2 \frac{\partial v}{\partial r} - 2r \frac{\partial^2 v}{\partial r^2} + \frac{4}{r} \frac{\partial^2 v}{\partial \theta^2} - 2 \frac{\partial^3 v}{\partial \theta^2 \partial r} + 2r \frac{\partial^4 v}{\partial \theta^2 \partial r^2} + \frac{1}{r} \frac{\partial^4 v}{\partial \theta^4} - \frac{v}{r}.
\end{aligned}$$

Therefore, we obtain that

$$r^3 \Delta^2 u = \Pi_1 + \Pi_2.$$

We set

$$w = \frac{v}{r}.$$

Then, in $S_{\omega, \rho}$, problem (7) becomes

$$\begin{cases} \frac{1}{r^3} \left[\left(r \frac{\partial}{\partial r}\right)^2 \left[\left(r \frac{\partial}{\partial r}\right)^2 w \right] + 2 \left(\frac{\partial^2}{\partial \theta^2} - 1\right) \left(r \frac{\partial}{\partial r}\right)^2 w + \left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 w \right] \\ - \frac{k}{r} \left[\left(\left(r \frac{\partial}{\partial r}\right)^2 w + 2 \left(r \frac{\partial}{\partial r}\right) w + w\right) + \frac{\partial^2 w}{\partial \theta^2} \right] = g \\ w(r, 0) = w(r, \omega) = \frac{\partial w}{\partial \theta}(r, 0) = \frac{\partial w}{\partial \theta}(r, \omega) = 0 \\ w(\rho, \theta) = \frac{\partial^2 w}{\partial \theta^2}(\rho, \theta) = \frac{\partial^2 w}{\partial \theta^2}(\rho, \theta) = 0. \end{cases} \quad (9)$$

Corollary 3.1. Let $g \in L^p_{\frac{1}{p}}(S_{\omega, \rho})$ with p satisfying assumption (8). Then, there exists $\rho_0 > 0$ such that problem (9) has a unique solution w satisfying

$$w \in W^{4, p}_{4-\frac{1}{p}}(S_{\omega, \rho_0}).$$

This result is a direct consequence of Theorem 2.2.

Remark 3.2. Note that, we can also verify that we have in addition: for $i = 0, 1, 2$ and $j = 0, 1, 2, 3, 4$ such that $0 \leq i + j \leq 4$

$$\frac{\partial^{i+j} w}{\partial r^i \partial \theta^j} \in L^p(S_{\omega, \rho_0}).$$

In fact, we have

$$\frac{\partial^3 w}{\partial r^3}, \frac{\partial^4 w}{\partial r^3 \partial \theta} \in L^p_{3-\frac{1}{p}}(S_{\omega, \rho_0}) \quad \text{and} \quad \frac{\partial^4 w}{\partial r^4} \in L^p_{4-\frac{1}{p}}(S_{\omega, \rho_0}),$$

see Section 4.2.2; but, these two weighted spaces are not embedded into the space $L^p(S_{\omega, \rho_0})$.

3.2 Vector formulation of problem (9)

Now, let us consider the vector variable $\Psi(r, \theta)$:

$$\Psi = \begin{pmatrix} w \\ \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix},$$

and the following matrix

$$\mathcal{A} = \begin{pmatrix} 0 & 1 \\ -\left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 & -2\left(\frac{\partial^2}{\partial \theta^2} - 1\right) \end{pmatrix}.$$

We have

$$\begin{aligned} & \left(r \frac{\partial}{\partial r}\right)^2 \Psi - \mathcal{A} \Psi \\ &= \begin{pmatrix} \left(r \frac{\partial}{\partial r}\right)^2 w \\ \left(r \frac{\partial}{\partial r}\right)^2 \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix} + \begin{pmatrix} -\left(r \frac{\partial}{\partial r}\right)^2 w \\ \left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 w + 2\left(\frac{\partial^2}{\partial \theta^2} - 1\right) \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ \left(r \frac{\partial}{\partial r}\right)^2 \left(r \frac{\partial}{\partial r}\right)^2 w + 2\left(\frac{\partial^2}{\partial \theta^2} - 1\right) \left(r \frac{\partial}{\partial r}\right)^2 w + \left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 w \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ \Pi_1 + \Pi_2 \end{pmatrix} = \begin{pmatrix} 0 \\ r^3 \Delta^2 u \end{pmatrix}. \end{aligned}$$

We set

$$\mathcal{A}_0 = \begin{pmatrix} 0 & 0 \\ \frac{\partial^2}{\partial \theta^2} + 1 & 1 \end{pmatrix} \quad \text{and} \quad \mathcal{B}_0 = \begin{pmatrix} 0 & 0 \\ 2\left(r \frac{\partial}{\partial r}\right) & 0 \end{pmatrix}.$$

We will precise the domain of all these operators in section 3.4. It is clear that the action of these operators are independent. Then

$$(\mathcal{A}_0 + \mathcal{B}_0) \Psi = \begin{pmatrix} 0 & 0 \\ \frac{\partial^2}{\partial \theta^2} + 1 & 1 \end{pmatrix} \begin{pmatrix} w \\ \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 2\left(r \frac{\partial}{\partial r}\right) & 0 \end{pmatrix} \begin{pmatrix} w \\ \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix},$$

hence

$$\begin{aligned}
(\mathcal{A}_0 + \mathcal{B}_0) \Psi &= \begin{pmatrix} 0 \\ \frac{\partial^2}{\partial \theta^2} w + w + \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \left(r \frac{\partial}{\partial r}\right) w \end{pmatrix} \\
&= \begin{pmatrix} 0 \\ 2r \frac{\partial}{\partial r} w + \frac{\partial^2}{\partial \theta^2} w + w + \left(r \frac{\partial}{\partial r}\right)^2 w \end{pmatrix} \\
&= \begin{pmatrix} 0 \\ r \Delta u \end{pmatrix} = r \begin{pmatrix} 0 \\ \Delta u \end{pmatrix}.
\end{aligned}$$

The generalized diffusion equation becomes

$$\frac{1}{r^3} \left[\left(r \frac{\partial}{\partial r}\right)^2 \Psi - \mathcal{A} \Psi \right] - \frac{k}{r} (\mathcal{A}_0 + \mathcal{B}_0) \Psi = \begin{pmatrix} 0 \\ g \end{pmatrix}.$$

Finally, we obtain the following complete equation

$$\left[\left(r \frac{\partial}{\partial r}\right)^2 \Psi - \mathcal{A} \Psi \right] - kr^2 \mathcal{A}_0 \Psi - kr^2 \mathcal{B}_0 \Psi = \begin{pmatrix} 0 \\ r^3 g \end{pmatrix}. \quad (10)$$

Note that linear operators \mathcal{A} and \mathcal{A}_0 act with respect to variable θ whereas operator \mathcal{B}_0 acts with respect to variable $r \frac{\partial}{\partial r}$.

3.3 New formulation in a finite cone

We apply the following variables and functions change

$$r = \rho e^{-t}, \quad \phi(t, \theta) = w(\rho e^{-t}, \theta) \quad \text{and} \quad g(\rho e^{-t}, \theta) = G(t, \theta),$$

then, it is easy to verify that

$$\left(r \frac{\partial}{\partial r}\right) w = -\frac{\partial \phi}{\partial t} \quad \text{and} \quad \left(r \frac{\partial}{\partial r}\right)^2 w = \left[r \frac{\partial}{\partial r} + r^2 \frac{\partial^2}{\partial r^2} \right] w = \frac{\partial^2 \phi}{\partial t^2}.$$

We set $\Phi(t, \theta) = \Psi(\rho e^{-t}, \theta)$; then

$$\Phi = \begin{pmatrix} \phi \\ \frac{\partial^2 \phi}{\partial t^2} \end{pmatrix}.$$

Therefore, equation (10) is now set on the strip $\Sigma = (0, +\infty) \times (0, \omega)$ in the following form

$$\begin{aligned}
&\left[\left(r \frac{\partial}{\partial r}\right)^2 \Psi - \mathcal{A} \Psi \right] - kr^2 \mathcal{A}_0 \Psi - kr^2 \mathcal{B}_0 [\Psi] \\
&= \left[\frac{\partial^2 \Phi}{\partial t^2} - \mathcal{A} \Phi \right] - k\rho^2 e^{-2t} \mathcal{A}_0 \Phi + k\rho^2 e^{-2t} \mathcal{B}_1 [\Phi] = \begin{pmatrix} 0 \\ \rho^3 e^{-3t} G \end{pmatrix},
\end{aligned}$$

where

$$\mathcal{B}_1 = \begin{pmatrix} 0 & 0 \\ -2 \frac{\partial}{\partial t} & 0 \end{pmatrix}.$$

The boundary conditions, in problem (9), on w become

$$\phi(r, 0) = \phi(r, \omega) = \frac{\partial \phi}{\partial \theta}(r, 0) = \frac{\partial \phi}{\partial \theta}(r, \omega) = 0.$$

As usual, we will use the vector valued notation:

$$\Phi(t)(\theta) := \Phi(t, \theta) = \begin{pmatrix} \phi(t, \theta) \\ \frac{\partial^2 \phi}{\partial t^2}(t, \theta) \end{pmatrix} = \begin{pmatrix} \phi(t, \cdot) \\ \frac{\partial^2 \phi}{\partial t^2}(t, \cdot) \end{pmatrix}(\theta) := \begin{pmatrix} \phi(t) \\ \frac{\partial^2 \phi}{\partial t^2}(t) \end{pmatrix}(\theta).$$

Hence, we deduce the following abstract vector valued equation

$$[\Phi''(t) - \mathcal{A}\Phi(t)] - k\rho^2 e^{-2t} \mathcal{A}_0 \Phi(t) + k\rho^2 e^{-2t} [\mathcal{B}_1 \Phi](t) = \begin{pmatrix} 0 \\ \rho^3 e^{-3t} G(t) \end{pmatrix},$$

where

$$[\mathcal{B}_1 \Phi](t) = \begin{pmatrix} 0 & 0 \\ -2\frac{\partial}{\partial t} & 0 \end{pmatrix} \begin{pmatrix} \phi \\ \frac{\partial^2 \phi}{\partial t^2} \end{pmatrix}(t) = \begin{pmatrix} 0 \\ -2\frac{\partial \phi}{\partial t}(t) \end{pmatrix}.$$

Note that \mathcal{A} and \mathcal{A}_0 act on $\Phi(t)$ with respect to θ , while \mathcal{B}_1 acts on Φ with respect to t .

Now, we have to solve on $(0, +\infty)$ the following problem

$$\begin{cases} \Phi''(t) - \mathcal{A}\Phi(t) - k\rho^2 e^{-2t} \mathcal{A}_0 \Phi(t) + k\rho^2 e^{-2t} [\mathcal{B}_1 \Phi](t) = \begin{pmatrix} 0 \\ \rho^3 e^{-3t} G(t) \end{pmatrix} \\ \Phi(0) = 0. \end{cases} \quad (11)$$

Remark 3.3. Note that the boundary condition at $t = +\infty$, will be included in the vector valued space containing the solution Φ .

3.4 Sums of linear operators

In this section, we are going to write problem (11) as a sum of linear operators, firstly in the following Banach space

$$X = W_0^{2,p}(0, \omega) \times L^p(0, \omega),$$

see (13) below and secondly, in $L^p(0, +\infty; X)$, see (14) below.

Here X is equipped, for instance, with the following norm

$$\left\| \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \right\|_X = \|\psi_1\|_{W_0^{2,p}(0, \omega)} + \|\psi_2\|_{L^p(0, \omega)},$$

where

$$W_0^{2,p}(0, \omega) = \left\{ \varphi \in W^{2,p}(0, \omega) : \varphi(0) = \varphi(\omega) = \varphi'(0) = \varphi'(\omega) = 0 \right\}.$$

Then, we define the linear operator \mathcal{A} by

$$\begin{cases} D(\mathcal{A}) & = [W^{4,p}(0, \omega) \cap W_0^{2,p}(0, \omega)] \times W_0^{2,p}(0, \omega) \subset X \\ \mathcal{A} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} & = \begin{pmatrix} \psi_2 \\ -\left(\frac{\partial^2}{\partial \theta^2} + 1\right)^2 \psi_1 - 2\left(\frac{\partial^2}{\partial \theta^2} - 1\right) \psi_2 \end{pmatrix}, \quad \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \in D(\mathcal{A}). \end{cases}$$

In the same way, we define operator \mathcal{A}_0 by

$$\begin{cases} D(\mathcal{A}_0) &= W_0^{2,p}(0, \omega) \times L^p(0, \omega) = X \\ \mathcal{A}_0 \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} &= \begin{pmatrix} 0 \\ \left(\frac{\partial^2}{\partial \theta^2} + 1\right) \psi_1 + \psi_2 \end{pmatrix}, \quad \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \in D(\mathcal{A}_0). \end{cases}$$

It is clear that $D(\mathcal{A}) \subset D(\mathcal{A}_0)$. Note that operator \mathcal{A}_0 is continuous from X into itself since

$$\begin{aligned} \left\| \mathcal{A}_0 \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \right\|_X &= \left\| \begin{pmatrix} 0 \\ \left(\frac{\partial^2}{\partial \theta^2} + 1\right) \psi_1 + \psi_2 \end{pmatrix} \right\|_X = \left\| \left(\frac{\partial^2}{\partial \theta^2} + 1\right) \psi_1 + \psi_2 \right\|_{L^p(0, \omega)} \\ &\leq \|\psi_1\|_{W_0^{2,p}(0, \omega)} + \|\psi_2\|_{L^p(0, \omega)} = \left\| \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} \right\|_X. \end{aligned}$$

Equation (11) is set in the Banach space X .

Recall that the second member in problem (2) satisfies

$$f \in L^p(S_{\omega, \rho}), \quad \text{for } p \in (1, +\infty).$$

Set

$$t \mapsto e^{-3t}G(t)(\cdot) = e^{-3t}G(t, \cdot) = H(t, \cdot) = H(t)(\cdot).$$

Therefore, we have

$$\begin{aligned} \int_{S_{\omega, \rho}} |f(x, y)|^p dx dy &= \int_{S_{\omega, \rho}} |g(r, \theta)|^p r dr d\theta = \rho^2 \int_{\Sigma} |G(t, \theta)|^p e^{-2t} dt d\theta \\ &= \rho^2 \int_{\Sigma} \left| e^{(3-\frac{2}{p})t} H(t, \theta) \right|^p dt d\theta \\ &= \rho^2 \int_0^{+\infty} \left| e^{(3-\frac{2}{p})t} \right|^p \left[\left(\int_0^{\omega} |H(t)(\theta)|^p d\theta \right)^{1/p} \right]^p dt \\ &= \rho^2 \int_0^{+\infty} e^{(3p-2)t} \|H(t)\|_{L^p(0, \omega)}^p dt. \end{aligned}$$

It follows that the second member H is in the weighted Sobolev space as recalled in (6)

$$\left\{ H : t \mapsto e^{(3-\frac{2}{p})t} H \in L^p(\Sigma) \right\} = L_{\nu}^p(0, +\infty; L^p(0, \omega)),$$

where

$$\nu = 3 - \frac{2}{p} \in (1, 3),$$

which is exactly the Sobolev exponent of the space $W^{3,p}(\Sigma)$ in dimension 2.

Then, since it would not be easy to work in weighted Sobolev spaces, we will use the following new vector valued function :

$$V(t) = e^{\nu t} \Phi(t) = \begin{pmatrix} e^{\nu t} \phi(t) \\ e^{\nu t} \phi''(t) \end{pmatrix} = \begin{pmatrix} V_1(t) \\ V_2(t) \end{pmatrix}. \quad (12)$$

Since we have

$$\Phi(t) = \begin{pmatrix} e^{-\nu t} V_1(t) \\ e^{-\nu t} V_2(t) \end{pmatrix},$$

we deduce that

$$\Phi'(t) = -\nu e^{-\nu t} V(t) + e^{-\nu t} V'(t) = e^{-\nu t} (\partial_t - \nu I) V(t),$$

and

$$\Phi''(t) = \nu^2 e^{-\nu t} V(t) - 2\nu e^{-\nu t} V'(t) + e^{-\nu t} V''(t) = e^{-\nu t} (\partial_t - \nu I)^2 V(t).$$

Moreover, we obtain

$$\begin{aligned} [\mathcal{B}_1 \Phi](t) &= \begin{pmatrix} 0 & 0 \\ -2\partial_t & 0 \end{pmatrix} \begin{pmatrix} e^{-\nu t} V_1(t) \\ e^{-\nu t} V_2(t) \end{pmatrix} \\ &= e^{-\nu t} \begin{pmatrix} 0 & 0 \\ -2(\partial_t - \nu I) & 0 \end{pmatrix} \begin{pmatrix} V_1(t) \\ V_2(t) \end{pmatrix} \\ &= e^{-\nu t} [\mathcal{B}_{2,\nu} V](t), \end{aligned}$$

where

$$\mathcal{B}_{2,\nu} = \begin{pmatrix} 0 & 0 \\ -2(\partial_t - \nu I) & 0 \end{pmatrix}.$$

Hence, problem (11) becomes

$$\begin{cases} e^{-\nu t} (\partial_t - \nu I)^2 V(t) - e^{-\nu t} \mathcal{A}V(t) - k\rho^2 e^{-\nu t} e^{-2t} \mathcal{A}_0 V(t) \\ -k\rho^2 e^{-\nu t} e^{-2t} [(\mathcal{B}_{2,\nu} V)](t) = \begin{pmatrix} 0 \\ \rho^3 H(t) \end{pmatrix} \\ V(0) = 0, \end{cases}$$

then

$$\begin{cases} (\partial_t - \nu I)^2 V(t) - \mathcal{A}V(t) - k\rho^2 e^{-2t} \mathcal{A}_0 V(t) - k\rho^2 e^{-2t} [(\mathcal{B}_{2,\nu} V)](t) = \begin{pmatrix} 0 \\ \rho^3 e^{\nu t} H(t) \end{pmatrix} \\ V(0) = 0. \end{cases} \quad (13)$$

We have

$$t \mapsto \rho^3 e^{\nu t} H(t) \in L^p(\Sigma) = L^p(0, +\infty; L^p(0, \omega)),$$

and

$$t \mapsto \begin{pmatrix} 0 \\ \rho^3 e^{\nu t} H(t) \end{pmatrix} \in L^p(0, +\infty; W_0^{2,p}(0, \omega) \times L^p(0, \omega)) = L^p(0, +\infty; X).$$

Finally, let us introduce the following abstract linear operators:

$$\begin{cases} D(\mathcal{L}_{1,\nu}) &= \{V \in W^{2,p}(0, +\infty; X) : V(0) = V(+\infty) = 0\} \\ [\mathcal{L}_{1,\nu}(V)](t) &= (\partial_t - \nu I)^2 V(t) = V''(t) - 2\nu V'(t) + \nu^2 V(t), \end{cases}$$

with $\nu = 3 - \frac{2}{p} \in (1, 3)$,

$$\begin{cases} D(\mathcal{L}_2) &= \{V \in L^p(0, +\infty; X) : \text{for a.e. } t \in (0, +\infty), V(t) \in D(\mathcal{A})\} \\ [\mathcal{L}_2(V)](t) &= -\mathcal{A}V(t), \end{cases}$$

$$\begin{cases} D(\mathcal{P}_1) &= \{V \in L^p(0, +\infty; X) : \text{for a.e. } t \in (0, +\infty), V(t) \in D(\mathcal{A}_0)\} \\ [\mathcal{P}_1(V)](t) &= -e^{-2t} \mathcal{A}_0 V(t), \end{cases}$$

and

$$\begin{cases} D(\mathcal{P}_{2,\nu}) & = W^{1,p}(0, +\infty; X) \\ [\mathcal{P}_{2,\nu}(V)](t) & = -e^{-2t} (\mathcal{B}_{2,\nu} V)(t). \end{cases}$$

Then, problem (13) can be written as the following abstract equation

$$(\mathcal{L}_{1,\nu} + \mathcal{L}_2) V + k\rho^2 (\mathcal{P}_1 + \mathcal{P}_{2,\nu}) V = \mathcal{F}_\nu, \quad (14)$$

set in $L^p(0, +\infty; X)$, with $p \in (1, +\infty)$, where, for almost every $t \in (0, +\infty)$

$$\mathcal{F}_\nu(t) = \begin{pmatrix} 0 \\ \rho^3 e^{\nu t} H(t) \end{pmatrix}.$$

4 Proof of Theorem 2.2

4.1 Resolution of equation (14)

Equation (14) will be completely studied in the second part of this work by using the sum theory of linear operators, where the main result described by Theorem 1.1 in Labbas, Maingot and Thorel [7] states that there exists $\rho_0 > 0$ such that for all $\rho \in (0, \rho_0]$, there exists a unique solution $V \in D(\mathcal{L}_{1,\nu} + \mathcal{L}_2)$ to equation (14) that is

$$V \in W^{2,p}(0, +\infty; X) \cap L^p(0, +\infty; D(\mathcal{A})).$$

Thus, we know that there exists a continuous extension from $W^{2,p}(0, +\infty; X)$ into $W^{2,p}(\mathbb{R}; X)$ and also from $L^p(0, +\infty; D(\mathcal{A}))$ into $L^p(\mathbb{R}; D(\mathcal{A}))$; it suffices, for instance to use the well-known Babich techniques.

Set \tilde{V} , the extension of V ; it is then written as

$$\tilde{V} = \begin{pmatrix} \tilde{V}_1 \\ \tilde{V}_2 \end{pmatrix}.$$

So

$$\tilde{V}_1 \in W^{2,p}(\mathbb{R}; W_0^{2,p}(0, \omega)) \cap L^p(\mathbb{R}; W^{4,p}(0, \omega) \cap W_0^{2,p}(0, \omega)),$$

and

$$\tilde{V}_2 \in W^{2,p}(\mathbb{R}; L^p(0, \omega)) \cap L^p(\mathbb{R}; W_0^{2,p}(0, \omega)).$$

From this two properties, we obtain

$$\tilde{V}_1, \tilde{V}_2 \in W^{2,p}(\mathbb{R} \times (0, \omega)),$$

and

$$\tilde{V}_1 \in W^{2,p}(\mathbb{R}; W_0^{2,p}(0, \omega)) \cap L^p(\mathbb{R}; W^{4,p}(0, \omega)),$$

by using the following lemma.

Lemma 4.1. Let $I =]a, b[$, $a < b$ be an open bounded subset of \mathbb{R} . Then

$$W^{2,p}(\mathbb{R}; L^p(I)) \cap L^p(\mathbb{R}; W^{2,p}(I)) \subset W^{2,p}(\mathbb{R} \times I).$$

Proof. Let $\chi \in W^{m,p}(a, b)$. Then $\chi \in C^{m-1}([a, b])$. Consider the Taylor polynomial

$$T_{m-1}(x) = \sum_{k=0}^{m-1} \frac{1}{k!} (x-b)^k \chi^{(k)}(b), \quad \text{for } x > b.$$

We define the following bump function $\varphi \in C^\infty([b, +\infty))$ such that

$$\varphi(x) = \begin{cases} 1 & \text{for } b \leq x \leq b+1 \\ 0 & \text{for } x \geq b+2. \end{cases}$$

Then $x \mapsto T_{m-1}(x)\varphi(x)$ belongs to $W^{m,p}(b, +\infty)$. Now, we define an extension function on $(a, +\infty)$ by

$$\tilde{\chi}(x) = \begin{cases} \chi(x) & \text{for } a < x < b \\ T_{m-1}(x)\varphi(x) & \text{for } x > b. \end{cases}$$

Clearly, $\tilde{\chi}$ belongs to $W^{m,p}(a, +\infty)$. Moreover, all the derivatives on the left and on the right, up to order $m-1$, coincide. In the same way, we build an extension to the left of point a . Consequently, there exists an extension operator P which maps continuously

$$L^p(I) \text{ into } L^p(\mathbb{R}) \text{ and } W^{2,p}(I) \text{ into } W^{2,p}(\mathbb{R}).$$

Therefore, for

$$\chi \in W^{2,p}(\mathbb{R}; L^p(I)) \cap L^p(\mathbb{R}; W^{2,p}(I)),$$

we have

$$P\chi \in W^{2,p}(\mathbb{R}; L^p(\mathbb{R})) \cap L^p(\mathbb{R}; W^{2,p}(\mathbb{R})).$$

This last space coincides with

$$W^{2,p}(\mathbb{R}^2),$$

by Mihlin's theorem (see Mihlin [9]).

Consequently, χ , the restriction of $P\chi$ to $\mathbb{R} \times I$, belongs to $W^{2,p}(\mathbb{R} \times I)$. \square

We take this opportunity to indicate a similar result in the case of a bounded open set of \mathbb{R}^n with $n > 1$.

Lemma 4.2. Let U be an open bounded subset of \mathbb{R}^n , $n > 1$, with a Lipschitz boundary. Then

$$W^{2,p}(\mathbb{R}; L^p(U)) \cap L^p(\mathbb{R}; W^{2,p}(U)) \subset W^{2,p}(\mathbb{R} \times U).$$

Proof. We know that there exists an extension operator P which maps continuously

$$L^p(U) \text{ into } L^p(\mathbb{R}^n) \text{ and } W^{2,p}(U) \text{ into } W^{2,p}(\mathbb{R}^n);$$

then for

$$\chi \in W^{2,p}(\mathbb{R}; L^p(U)) \cap L^p(\mathbb{R}; W^{2,p}(U)),$$

we have

$$P\chi \in W^{2,p}(\mathbb{R}; L^p(\mathbb{R}^n)) \cap L^p(\mathbb{R}; W^{2,p}(\mathbb{R}^n)).$$

This last space coincide with

$$W^{2,p}(\mathbb{R}^{n+1}),$$

by Mihlin's theorem (see Mihlin [9]).

Consequently, χ , the restriction of $P\chi$ to $\mathbb{R} \times U$, belongs to $W^{2,p}(\mathbb{R} \times U)$. \square

Therefore, we deduce that V_1 and V_2 have the same regularities on $(0, \rho) \times (0, \omega)$, with $\rho \in (0, \rho_0]$.

4.2 Regularities of $v(r, \theta)$ and $w(r, \theta) = v(r, \theta)/r$

In the sequel, all the regularities of w are deduced easily from those of v .

Recall that, from (12), we have

$$V(t) = e^{\nu t} \Phi(t) \quad \text{and} \quad \Phi(t) = e^{-\nu t} V(t).$$

Moreover, since $r = \rho e^{-t}$, we obtain

$$V_1(t, \theta) = \frac{v(\rho e^{-t}, \theta)}{(\rho e^{-t})^{\nu+1}},$$

where $\nu = 3 - \frac{2}{p} \in (1, 3)$ and

$$V_2(t, \theta) = \left(r \frac{\partial}{\partial r} \right)^2 \left(\frac{v}{r} \right) (\rho e^{-t}, \theta) = (\rho e^{-t}) \frac{\partial^2 v}{\partial r^2} (\rho e^{-t}, \theta) - \frac{\partial v}{\partial r} (\rho e^{-t}, \theta) + \frac{v(\rho e^{-t}, \theta)}{\rho e^{-t}}.$$

4.2.1 Regularity of V_1

Here, we explicit the fact that

$$V_1 \in W^{2,p}((0, +\infty) \times (0, \omega)). \quad (15)$$

We have

$$\int_0^{+\infty} \int_0^\omega |V_1(t, \theta)|^p d\theta dt = \int_0^{+\infty} \int_0^\omega \left| \frac{v(\rho e^{-t}, \theta)}{\rho^{\nu+1} e^{-t(\nu+1)}} \right|^p d\theta dt < +\infty.$$

Setting $r = \rho e^{-t}$, we obtain

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \frac{v(\rho e^{-t}, \theta)}{(\rho e^{-t})^{\nu+1}} \right|^p d\theta dt &= \int_0^\rho \int_0^\omega \left| \frac{v(r, \theta)}{r^{\nu+1+\frac{1}{p}}} \right|^p d\theta dr \\ &= \int_0^\rho \int_0^\omega r^{-4p+1} |v(r, \theta)|^p d\theta dr. \end{aligned}$$

Then, we have

$$v \in L^p_{\gamma_0}(S_{\omega, \rho}) \quad \text{and} \quad w = \frac{v}{r} \in L^p_{\gamma_0+1}(S_{\omega, \rho}), \quad (16)$$

where $\gamma_0 = -4 + \frac{1}{p}$. Moreover

$$\begin{aligned} \frac{\partial V_1}{\partial t}(t, \theta) &= \frac{1}{\rho^{\nu+1}} \frac{\partial}{\partial t} \left(v(\rho e^{-t}, \theta) e^{(\nu+1)t} \right) \\ &= \frac{1}{\rho^{\nu+1}} \left((\nu+1) e^{(\nu+1)t} v(\rho e^{-t}, \theta) - \rho e^{\nu t} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) \right), \end{aligned}$$

hence

$$\frac{1}{(\rho e^{-t})^\nu} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) = \frac{(\nu+1)}{(\rho e^{-t})^{\nu+1}} v(\rho e^{-t}, \theta) - \frac{\partial V_1(t, \theta)}{\partial t}.$$

Thus, in virtue of (15) and (16), it follows that

$$(t, \theta) \mapsto \frac{1}{(\rho e^{-t})^\nu} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) \in L^p((0, +\infty) \times (0, \omega)),$$

and

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \frac{1}{(\rho e^{-t})^\nu} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) \right|^p d\theta dt &= \int_0^\rho \int_0^\omega \left| \frac{1}{r^{\nu+\frac{1}{p}}} \frac{\partial v}{\partial r}(r, \theta) \right|^p d\theta dr \\ &= \int_0^\rho \int_0^\omega r^{-3p+1} \left| \frac{\partial v}{\partial r}(r, \theta) \right|^p d\theta dr. \end{aligned}$$

So, we obtain

$$\frac{\partial v}{\partial r} \in L_{\gamma_1}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial w}{\partial r} \in L_{\gamma_1+1}^p(S_{\omega, \rho}), \quad (17)$$

where $\gamma_1 = -3 + \frac{1}{p}$. Furthermore, we have

$$\begin{aligned} \frac{\partial^2 V_1}{\partial t^2}(t, \theta) &= \frac{\nu+1}{\rho^{\nu+1}} \frac{\partial}{\partial t} \left(v(\rho e^{-t}, \theta) e^{(\nu+1)t} \right) - \frac{\nu}{\rho^\nu} e^{\nu t} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) + \frac{\rho}{\rho^\nu} e^{-t} e^{\nu t} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) \\ &= \frac{\nu+1}{\rho^{\nu+1}} \left((\nu+1) e^{(\nu+1)t} v(\rho e^{-t}, \theta) - \rho e^{\nu t} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) \right) - \frac{\nu}{\rho^\nu} e^{\nu t} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) \\ &\quad + \frac{1}{\rho^{\nu-1}} e^{(\nu-1)t} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) \\ &= \frac{(\nu+1)^2}{(\rho e^{-t})^{\nu+1}} v(\rho e^{-t}, \theta) - \frac{2\nu+1}{(\rho e^{-t})^\nu} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) + \frac{1}{(\rho e^{-t})^{\nu-1}} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta), \end{aligned}$$

hence

$$\frac{1}{(\rho e^{-t})^{\nu-1}} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) = \frac{\partial^2 V_1}{\partial t^2}(t, \theta) + \frac{2\nu+1}{(\rho e^{-t})^\nu} \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) - \frac{(\nu+1)^2}{(\rho e^{-t})^{\nu+1}} v(\rho e^{-t}, \theta).$$

Thus, in virtue of (15), (16) and (17), it follows that

$$(t, \theta) \mapsto \frac{1}{(\rho e^{-t})^{\nu-1}} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) \in L^p((0, +\infty) \times (0, \omega)),$$

and

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \frac{1}{(\rho e^{-t})^{\nu-1}} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) \right|^p d\theta dt &= \int_0^\rho \int_0^\omega \left| \frac{1}{r^{\nu-1+\frac{1}{p}}} \frac{\partial^2 v}{\partial r^2}(r, \theta) \right|^p d\theta dr \\ &= \int_0^\rho \int_0^\omega r^{-2p+1} \left| \frac{\partial^2 v}{\partial r^2}(r, \theta) \right|^p d\theta dr. \end{aligned}$$

So, we obtain

$$\frac{\partial^2 v}{\partial r^2} \in L_{\gamma_2}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^2 w}{\partial r^2} \in L_{\gamma_2+1}^p(S_{\omega, \rho}),$$

where $\gamma_2 = -2 + \frac{1}{p}$.

On the other hand

$$\frac{\partial V_1}{\partial \theta}(\rho e^{-t}, \theta) = \frac{1}{(\rho e^{-t})^{\nu+1}} \frac{\partial v}{\partial \theta}(\rho e^{-t}, \theta).$$

Thus, it follows that

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \frac{\partial V_1}{\partial \theta}(\rho e^{-t}, \theta) \right|^p d\theta dt &= \int_0^{+\infty} \int_0^\omega \frac{1}{(\rho e^{-t})^{p(\nu+1)}} \left| \frac{\partial v}{\partial \theta}(\rho e^{-t}, \theta) \right|^p d\theta dt \\ &= \int_0^\rho \int_0^\omega r^{-4p+1} \left| \frac{\partial v}{\partial \theta}(r, \theta) \right|^p d\theta dr. \end{aligned}$$

So, we obtain

$$\frac{\partial v}{\partial \theta} \in L_{\gamma_0}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial w}{\partial \theta} \in L_{\gamma_0+1}^p(S_{\omega, \rho}).$$

In the same way, we deduce that

$$\frac{\partial^2 v}{\partial \theta^2} \in L_{\gamma_0}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^2 v}{\partial r \partial \theta} \in L_{\gamma_1}^p(S_{\omega, \rho}),$$

hence

$$\frac{\partial^2 w}{\partial \theta^2} \in L_{\gamma_0+1}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^2 w}{\partial r \partial \theta} \in L_{\gamma_1+1}^p(S_{\omega, \rho}).$$

Now, we explicit the fact that

$$\frac{\partial^3 V_1}{\partial t \partial \theta^2}, \frac{\partial^3 V_1}{\partial t^2 \partial \theta}, \frac{\partial^4 V_1}{\partial t^2 \partial \theta^2} \in L^p((0, +\infty) \times (0, \omega)).$$

We have

$$\frac{\partial^3 V_1}{\partial t^2 \partial \theta}(t, \theta) = \frac{(\nu+1)^2}{(\rho e^{-t})^{\nu+1}} \frac{\partial v}{\partial \theta}(\rho e^{-t}, \theta) - \frac{2\nu+1}{(\rho e^{-t})^\nu} \frac{\partial^2 v}{\partial r \partial \theta}(\rho e^{-t}, \theta) + \frac{1}{(\rho e^{-t})^{\nu-1}} \frac{\partial^3 v}{\partial r^2 \partial \theta}(\rho e^{-t}, \theta),$$

hence

$$\frac{1}{(\rho e^{-t})^{\nu-1}} \frac{\partial^3 v}{\partial r^2 \partial \theta}(\rho e^{-t}, \theta) = \frac{\partial^3 V_1}{\partial t^2 \partial \theta}(t, \theta) - \frac{(\nu+1)^2}{(\rho e^{-t})^{\nu+1}} \frac{\partial v}{\partial \theta}(\rho e^{-t}, \theta) + \frac{2\nu+1}{(\rho e^{-t})^\nu} \frac{\partial^2 v}{\partial r \partial \theta}(\rho e^{-t}, \theta).$$

Thus, we obtain

$$\frac{\partial^3 v}{\partial r^2 \partial \theta} \in L_{\gamma_2}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^3 w}{\partial r^2 \partial \theta} \in L_{\gamma_2+1}^p(S_{\omega, \rho}),$$

and in the same way, we also have

$$\frac{\partial^3 v}{\partial r \partial \theta^2} \in L_{\gamma_1}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^4 v}{\partial r^2 \partial \theta^2} \in L_{\gamma_2}^p(S_{\omega, \rho}),$$

hence

$$\frac{\partial^3 w}{\partial r \partial \theta^2} \in L_{\gamma_1+1}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^4 w}{\partial r^2 \partial \theta^2} \in L_{\gamma_2+1}^p(S_{\omega, \rho}).$$

Now, we explicit the fact that

$$V_1 \in L^p((0, +\infty); W^{4,p}(0, \omega)),$$

that is, for all $i = 1, 2, 3, 4$

$$\int_0^{+\infty} \left\| \frac{\partial^i V_1}{\partial \theta^i}(t, \theta) \right\|_{L^p(0, \omega)}^p dt < +\infty.$$

Then, we have

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \frac{\partial^i V_1}{\partial \theta^i}(t, \theta) \right|^p d\theta dt &= \int_0^{+\infty} \int_0^\omega \left| \frac{1}{(\rho e^{-t})^{\nu+1}} \frac{\partial^i v}{\partial \theta^i}(\rho e^{-t}, \theta) \right|^p d\theta dt \\ &= \int_0^\rho \int_0^\omega r^{-4p+1} \left| \frac{\partial^i v}{\partial \theta^i}(r, \theta) \right|^p d\theta dr, \end{aligned}$$

which gives

$$\frac{\partial^i v}{\partial \theta^i} \in L_{\gamma_0}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^i w}{\partial \theta^i} \in L_{\gamma_0+1}^p(S_{\omega, \rho}), \quad \text{for } i = 1, 2, 3, 4.$$

4.2.2 Regularity of V_2

In the same way, we explicit the fact that

$$V_2 \in W^{2,p}((0, +\infty) \times (0, \omega)),$$

where

$$V_2(t, \theta) = \left(r \frac{\partial}{\partial r} \right)^2 \left(\frac{v}{r} \right) (\rho e^{-t}, \theta) = \rho e^{-t} \frac{\partial^2 v}{\partial r^2} (\rho e^{-t}, \theta) - \frac{\partial v}{\partial r} (\rho e^{-t}, \theta) + \frac{v(\rho e^{-t}, \theta)}{\rho e^{-t}}.$$

It is clear, from Subsection 4.2.1, that

$$r \frac{\partial^2 v}{\partial r^2}, \frac{\partial v}{\partial r}, \frac{v}{r} \in L_{\gamma_1}^p(S_{\omega, \rho}).$$

Moreover, we have

$$\frac{\partial V_2}{\partial t}(t, \theta) = - \left(\rho e^{-t} \right)^2 \frac{\partial^3 v}{\partial r^3} (\rho e^{-t}, \theta) - \frac{\partial v}{\partial r} (\rho e^{-t}, \theta) + \frac{v(\rho e^{-t}, \theta)}{\rho e^{-t}},$$

hence

$$\left(\rho e^{-t} \right)^2 \frac{\partial^3 v}{\partial r^3} (\rho e^{-t}, \theta) = - \frac{\partial v}{\partial r} (\rho e^{-t}, \theta) + \frac{v(\rho e^{-t}, \theta)}{\rho e^{-t}} - \frac{\partial V_2}{\partial t}(t, \theta).$$

Then

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \frac{\partial v}{\partial r} (\rho e^{-t}, \theta) \right|^p d\theta dt &= \int_0^\rho \int_0^\omega \frac{r^{3p-1}}{r} r^{-3p+1} \left| \frac{\partial v}{\partial r}(r, \theta) \right|^p d\theta dr \\ &\leq \rho^{3p-2} \int_0^\rho \int_0^\omega r^{-3p+1} \left| \frac{\partial v}{\partial r}(r, \theta) \right|^p d\theta dr < +\infty. \end{aligned}$$

It follows that

$$\int_0^{+\infty} \int_0^\omega \left| \left(\rho e^{-t} \right)^2 \frac{\partial^3 v}{\partial r^3} (\rho e^{-t}, \theta) \right|^p d\theta dt = \int_0^\rho \int_0^\omega r^{2p-1} \left| \frac{\partial^3 v}{\partial r^3}(r, \theta) \right|^p d\theta dr < +\infty,$$

which means that

$$\frac{\partial^3 v}{\partial r^3} \in L_{\gamma_3}^p(S_{\omega, \rho}), \quad \text{and} \quad \frac{\partial^3 w}{\partial r^3} \in L_{\gamma_3+1}^p(S_{\omega, \rho}),$$

where $\gamma_3 = 2 - \frac{1}{p}$.

In the same way, we have

$$\frac{\partial^4 v}{\partial r \partial \theta^3} \in L_{\gamma_1}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^4 v}{\partial r^3 \partial \theta} \in L_{\gamma_3}^p(S_{\omega, \rho}),$$

hence

$$\frac{\partial^4 w}{\partial r \partial \theta^3} \in L_{\gamma_1+1}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^4 w}{\partial r^3 \partial \theta} \in L_{\gamma_3+1}^p(S_{\omega, \rho}).$$

Furthermore, we have

$$\begin{aligned} \frac{\partial^2 V_2}{\partial t^2}(t, \theta) &= \left(\rho e^{-t} \right)^3 \frac{\partial^4 v}{\partial r^4} (\rho e^{-t}, \theta) + 2 \left(\rho e^{-t} \right)^2 \frac{\partial^3 v}{\partial r^3} (\rho e^{-t}, \theta) + \rho e^{-t} \frac{\partial^2 v}{\partial r^2} (\rho e^{-t}, \theta) \\ &\quad - \frac{\partial v}{\partial r} (\rho e^{-t}, \theta) - \frac{v(\rho e^{-t}, \theta)}{\rho e^{-t}}. \end{aligned}$$

Since

$$\begin{aligned} (\rho e^{-t})^3 \frac{\partial^4 v}{\partial r^4}(\rho e^{-t}, \theta) &= -2 (\rho e^{-t})^2 \frac{\partial^3 v}{\partial r^3}(\rho e^{-t}, \theta) - \rho e^{-t} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) \\ &\quad + \frac{\partial v}{\partial r}(\rho e^{-t}, \theta) + \frac{v(\rho e^{-t}, \theta)}{\rho e^{-t}} + \frac{\partial^2 V_2}{\partial t^2}(t, \theta), \end{aligned}$$

and

$$\begin{aligned} \int_0^{+\infty} \int_0^\omega \left| \rho e^{-t} \frac{\partial^2 v}{\partial r^2}(\rho e^{-t}, \theta) \right|^p d\theta dt &= \int_0^\rho \int_0^\omega \frac{r^{3p-1}}{r} r^{-3p+1} \left| r \frac{\partial^2 v}{\partial r^2}(r, \theta) \right|^p d\theta dr \\ &= \int_0^\rho \int_0^\omega r^{3p-2} r^{-3p+1} \left| r \frac{\partial^2 v}{\partial r^2}(r, \theta) \right|^p d\theta dr \\ &\leq \rho^{3p-2} \int_0^\rho \int_0^\omega r^{-3p+1} \left| r \frac{\partial^2 v}{\partial r^2}(r, \theta) \right|^p d\theta dr < +\infty, \end{aligned}$$

we deduce that

$$\int_0^{+\infty} \int_0^\omega \left| (\rho e^{-t})^3 \frac{\partial^4 v}{\partial r^4}(\rho e^{-t}, \theta) \right|^p d\theta dt = \int_0^\rho \int_0^\omega r^{3p-1} \left| \frac{\partial^4 v}{\partial r^4}(r, \theta) \right|^p d\theta dr < +\infty.$$

Therefore

$$\frac{\partial^4 v}{\partial r^4} \in L_{\gamma_4}^p(S_{\omega, \rho}) \quad \text{and} \quad \frac{\partial^4 w}{\partial r^4} \in L_{\gamma_4+1}^p(S_{\omega, \rho}),$$

where $\gamma_4 = 3 - \frac{1}{p}$.

It is clear now that the appropriated weight function, cited in (6), is $r \mapsto r^\gamma := r^{3 - \frac{1}{p}}$.

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Conflict of interest

On behalf of all authors, the corresponding author states that there is no conflict of interest.

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